THE ASSEMBLY,

RECALLING Article 16(i) of the Convention on the Inter-Governmental Maritime Consultative Organization,

BEARING IN MIND the provisions of Regulation 12, Chapter V, of the International Convention for the Safety of Life at Sea, 1974, and the proposed amendments to that regulation,

RECALLING ALSO resolution A.222(VII) by which it adopted performance standards for radar equipment,

RECOGNIZING the desirability of making such performance standards compatible with the Performance Standards for Automatic Radar Plotting Aids (ARPA) (resolution A.422(XI)) and with resolution A.423(XI) on radar beacons and transponders,

HAVING CONSIDERED the recommendation made by the Maritime Safety Committee at its forty-second session,

1. ADOPTS the Recommendation on Performance Standards for Radar Equipment set out in the Annex to the present resolution;

2. RECOMMENDS Member Governments to ensure that:

(a) Radar equipment installed on or after 1 September 1984 conforms to performance standards not inferior to those specified in the Annex to the present resolution;

(b) Radar equipment installed before 1 September 1984 conforms at least to the performance standards set out in resolution A.222(VII).
ANNEX

RECOMMENDATION ON PERFORMANCE STANDARDS
FOR RADAR EQUIPMENT

1 Application

1.1 This Recommendation applies to all ships' radar equipment installed on or after 1 September 1984 in compliance with Regulation 12, Chapter V of the International Convention for the Safety of Life at Sea, 1974, as amended.

1.2 Radar equipment installed before 1 September 1984 should comply at least with the performance standards recommended in resolution A.222(VII).

2 General

The radar equipment should provide an indication, in relation to the ship, of the position of other surface craft and obstructions and of buoys, shorelines and navigational marks in a manner which will assist in navigation and in avoiding collision.

3 All radar installations

All radar installations should comply with the following minimum requirements.

3.1 Range performance

The operational requirement under normal propagation conditions, when the radar antenna is mounted at a height of 15 metres above sea level, is that the equipment should in the absence of clutter give a clear indication of:

1. Coastlines

At 20 nautical miles when the ground rises to 60 metres.
At 7 nautical miles when the ground rises to 6 metres.

2. Surface objects

At 7 nautical miles a ship of 5,000 tons gross tonnage, whatever her aspect.
At 3 nautical miles a small vessel of 10 metres in length.
At 2 nautical miles an object such as a navigational buoy having an effective echoing area of approximately 10 square metres.
3.2 Minimum range

The surface objects specified in 3.1.2 should be clearly displayed from a minimum range of 50 metres up to a range of one nautical mile, without changing the setting of controls other than the range selector.

3.3 Display

3.3.1 The equipment should without external magnification provide a relative plan display in the head-up unstabilized mode with an effective diameter of not less than:

- 180 millimetres* on ships of 500 tons gross tonnage and more but less than 1,600 tons gross tonnage;
- 250 millimetres* on ships of 1,600 tons gross tonnage and more but less than 10,000 tons gross tonnage;
- 340 millimetres* in the case of one display and 250 millimetres in the case of the other on ships of 10,000 tons gross tonnage and upwards.

3.3.2 The equipment should provide one of the two following sets of range scales of display:

- 1, 1.5, 3, 6, 12 and 24 nautical miles and one range scale of not less than 0.5 and not greater than 0.8 nautical miles; or
- 1, 2, 4, 8, 16 and 32 nautical miles.

3.3.3 Additional range scales may be provided.

3.3.4 The range scale displayed and the distance between range rings should be clearly indicated at all times.

3.4 Range measurement

3.4.1 Fixed electronic range rings should be provided for range measurements as follows:

- where range scales are provided in accordance with 3.3.2.1, on the range scale of between 0.5 and 0.8 nautical miles at least two range rings should be provided and on each of the other range scales six range rings should be provided, or

* Display diameters of 180, 250 and 340 millimetres correspond respectively to 9, 12 and 16 inch cathode ray tubes.
2. Where range scales are provided in accordance with 3.3.2.2,
four range rings should be provided on each of the range scales.

3.4.2 A variable electronic range marker should be provided with a numeric
readout of range.

3.4.3 The fixed range rings and the variable range marker should enable the
range of an object to be measured with an error not exceeding 1.5 per cent of
the maximum range of the scale in use, or 70 metres, whichever is the greater.

3.4.4 It should be possible to vary the brilliance of the fixed range rings
and the variable range marker and to remove them completely from the display.

3.5 Heading indicator

3.5.1 The heading of the ship should be indicated by a line on the display
with a maximum error not greater than plus or minus 1 degree. The thickness
of the displayed heading line should not be greater than 0.5 degrees.

3.5.2 Provision should be made to switch off the heading indicator by a
device which cannot be left in the "heading marker off" position.

3.6 Bearing measurement

3.6.1 Provision should be made to obtain quickly the bearing of any object
whose echo appears on the display.

3.6.2 The means provided for obtaining bearings should enable the bearing of
a target whose echo appears at the edge of the display to be measured with an
accuracy of plus or minus 1 degree or better.

3.7 Discrimination

3.7.1 The equipment should be capable of displaying as separate indications
on a range scale of 2 nautical miles or less, two small similar targets at a
range of between 50 per cent and 100 per cent of the range scale in use, and
on the same azimuth, separated by not more than 50 metres in range.

3.7.2 The equipment should be capable of displaying as separate indications
two small similar targets both situated at the same range between 50 per cent
and 100 per cent of the 1.5 or 2 mile range scales, and separated by not more
than 2.5 degrees in azimuth.

3.8 Roll or pitch

The performance of the equipment should be such that when the ship is
rolling or pitching up to plus or minus 10 degrees the range performance
requirements of 3.1 and 3.2 continue to be met.
3.9 Scan

The scan should be clockwise, continuous and automatic through 360 degrees of azimuth. The scan rate should be not less than 12 revolutions per minute. The equipment should operate satisfactorily in relative wind speeds of up to 100 knots.

3.10 Azimuth stabilization

3.10.1 Means should be provided to enable the display to be stabilized in azimuth by a transmitting compass. The equipment should be provided with a compass input to enable it to be stabilized in azimuth. The accuracy of alignment with the compass transmission should be within 0.5 degrees with a compass rotation rate of 2 revolutions per minute.

3.10.2 The equipment should operate satisfactorily in the unstabilized mode when the compass control is inoperative.

3.11 Performance check

Means should be available, while the equipment is used operationally, to determine readily a significant drop in performance relative to a calibration standard established at the time of installation, and to check that the equipment is correctly tuned in the absence of targets.

3.12 Anti-clutter devices

Suitable means should be provided for the suppression of unwanted echoes from sea clutter, rain and other forms of precipitation, clouds and sandstorms. It should be possible to adjust manually and continuously the anti-clutter controls. Anti-clutter controls should be inoperative in the fully anti-clockwise positions. In addition, automatic anti-clutter controls may be provided; however, they must be capable of being switched off.

3.13 Operation

3.13.1 The equipment should be capable of being switched on and operated from the display position.

3.13.2 Operational controls should be accessible and easy to identify and use. Where symbols are used they should comply with the recommendations of the Organization on symbols for controls on marine navigational radar equipment.

3.13.3 After switching on from cold the equipment should become fully operational within 4 minutes.
3.13.4 A standby condition should be provided from which the equipment can be brought to an operational condition within 15 seconds.

3.14 Interference

After installation and adjustment on board, the bearing accuracy as prescribed in this Recommendation should be maintained without further adjustment irrespective of the movement of the ship in the earth's magnetic field.

3.15 Sea or ground stabilization (true motion display)

3.15.1 Where sea or ground stabilization is provided the accuracy and discrimination of the display should be at least equivalent to that required by this Recommendation.

3.15.2 The motion of the trace origin should not, except under manual override conditions, continue to a point beyond 75 per cent of the radius of the display. Automatic resetting may be provided.

3.16 Antenna system

The antenna system should be installed in such a manner that the design efficiency of the radar system is not substantially impaired.

3.17 Operation with radar beacons

3.17.1 All radars operating in the 3 centimetre band should be capable of operating in a horizontally polarized mode.

3.17.2 It should be possible to switch off those signal processing facilities which might prevent a radar beacon from being shown on the radar display.

4 Multiple radar installations

4.1 Where two radars are required to be carried they should be so installed that each radar can be operated individually and both can be operated simultaneously without being dependent upon one another. When an emergency source of electrical power is provided in accordance with the appropriate requirements of Chapter II-1 of the 1974 SOLAS Convention, both radars should be capable of being operated from this source.

4.2 Where two radars are fitted, interswitching facilities may be provided to improve the flexibility and availability of the overall radar installation. They should be so installed that failure of either radar would not cause the supply of electrical energy to the other radar to be interrupted or adversely affected.